## y OmROn

## THE NEW V1000 INVERTER $10 \times 100=1$



Designed for
» 10 years lifetime
»100\% expectation match
» 1 in 10,000 field failure rate

## y OmROn

## Quality has a new formula

The V1000 Inverter is the result of years of experience as the European market leader and represents a revolution in inverter design. Compact and sensor-less, the V1000 has all of the features and performance that you have grown to expect from the world's leading inverter/drive manufacturer. But you have not met an inverter quite like the V1000.


## yomron <br> V1000



Features of the V1000 Inverter

- Up to 15 kW
- World's smallest compact inverter
- Built-in filter
- 10-years service life
- Control terminal board with memory (Patent pending)
- Faster CPU's
- Current vector control
- Low-noise technology (Patent pending)
- IM \& PM Motor control
- On-line tuning (Patent pending)
- Safety embedded


New Heatsink temperature evaluation

## Mechanical advances

The V1000 design has not only reduced volume by up to $40 \%$ compared with previous inverters, tests prove that it has increased vibration resistance from 20 Hz to $50 \mathrm{~Hz}(0.6 \mathrm{G})$ and heat dissipation has also been greatly increased, thanks to a new, hybrid heat-sink system (patent pending).


Failure rate for drives

## Proven reliability

To improve quality even further, a complete revision of production lines has taken place and human error has been reduced by installing the most advanced robotic technology available. The result is an expected failure rate of less than $0.01 \%$.


Conventional inverter vs V1000

## Performance guaranteed

V1000 is able to increase the output current by around $20 \%$ when moving down in frequency carrier thanks to its double rating. The standard setting is heavy duty (HD: $150 \%$ rated current/ 1 min ) and increasing output current when in the normal duty mode (ND: 120\% rated current/ 1 Min ).


## Time and space saving 100\% guaranteed



Space-saving side-by-side mounting
Remember when side-by-side mounting meant having to leave spaces for ventilation? Well, not with the V1000. A special alloy, hybrid cooling fin (patent pending) allows you to mount multiple units close together without overheating problems and saving vast amounts of panel space.


Time-saving screw-less terminals
Have you ever stopped to think how much time it takes to wire hundreds of terminals with twelve screws per inverter? With the V1000, you can reduce installation time (and therefore costs) considerably thanks to the use of screw-less terminals.


## Cost-saving EMC filter

A built-in EMC filter will save you the task of having to take special precautions for EMC shielding during installation. The optional, factoryinstalled filter will not only save on installation costs, it also reduces the bill of materials for external parts and simplifies logistics.


## Work-saving set-up

Setting up Omron inverter and servo drives is now easier than ever, following the release of a new version of the company's versatile CX-Drive drive configuration software package.

New features, all of which save time, include automatic recognition of drive series and type, an oscilloscope function, and facilities for connecting a single PC running Configurator to multiple drives. During parameter selection, all parameters are fully described, and many, including those associated with PID loops and jump frequency operation, are set with the aid of graphical control diagrams. Extensive help screens and tool tips are also provided. In addition to aiding drive setup, Omron's CX-Drive also provides comprehensive facilities, status indications and alarms to assist with commissioning and fault-finding. Drive inputs and outputs can be monitored in real time, while the oscilloscope function allows detailed analysis of drive operation, without the need for additional test equipment CX-Drive enhances connectivity through Omron's PLC and motion controllers by supporting DeviceNet, SCU, Mechatrolink and Profibus connectivity.


## Convenient on-line tuning

Unlike previous inverters, the V1000 has a smart 'on-line tuning' feature that takes 'auto-tuning' a stage further. This continuous method of tuning ensures that any temperature deviation large enough to affect electrical parameters governing the motor speed will be adjusted before any speed variance can occur.


## Time-saving safety feature

Safety is embedded in the V1000 from the inside out, making it easy for you to integrate the inverter into your machine system and avoid difficult connections to safety controllers. Dual safety inputs (acc. To EN954-1 Safety Category 3) will disconnect the motor faster at the first sign of trouble, while reducing external wiring and contactors.

## Advanced performance



Speed Fluctuation Rates


Speed Response Accuracy

## Accurate speed control

Unlike previous inverters, the V1000 delivers optimum speed control and high starting torque thanks to the current vector control. As opposed to other techniques, such as voltage vector control, current vector control uses the flux current, which is an actual measurement rather than an estimated value.

## Fast scan cycle

The V1000 employs a dual CPU concept with a CPU device that is four times faster than those on board previous inverters. This means a faster-than-ever scan cycle that boosts motor control performance, especially in current vector control applications where speed is of the essence.

## Silent operation

A feature of the V1000 that will delight your customers is the noise-suppression function that decreases motor noise at low carrier frequencies. This puts machine operators at less risk to safety hazards and has a positive effect on the general working ambience.


## Save repetition

Control parameters need only be set once with the V1000. They are automatically saved to a control terminal board memory that allows you to replace an inverter and simply forget it. The new inverter will be immediately updated with the current settings.

## Easy maintenance



Minimize downtime
The V1000 has an ingenious pre-maintenance function that will calculate the condition of electronic components and advise about their replacement based not only on the number of hours they have been in service, but also on factors such as stress due to load, temperature, the number of times they have been powered up, output frequency and carrier frequency, etc.


Main Power Supply

## Keeps running

Assuring that new data and communications keep flowing in the event of a power failure is critical in many applications. Naturally, the V1000 is available with a 24 Vdc power supply that will keep the CPU working in any power-down situation.

## y OmROn

## vz <br> V1000

## More performance \& Quality in less space

- Current vector control
- High starting torque ( $200 \%$ / 0.5 Hz )
- 1:100 speed control range
- Double rating ND 120\%/1min and HD 150\%/1 min
- IM\&PM motor control
- Online Tuning
- Low-noise Low carrier technology
- 10 years lifetime design
- Built-in filter
- Screw-less terminals
- Control Terminals with memory backup
- 24 VDC control board power supply option
- Fieldbus communications: Modbus, Profibus, CanOpen, DeviceNet, Lonworks, CompoNet, Ethernet
- Safety embedded (EN954-1 safety cat. 3)
- CE, UL, cUL and TUV


## Ratings

- 200 V Class single-phase 0.1 to 4 kW
- 200 V Class three-phase 0.1 to 15 kW
- 400 V Class three-phase 0.2 to 15 kW

System configuration


## Specifications

## Type designation



200 V class

| Single-phase: VZ- $\square$ |  | B0P1 | B0P2 | B0P4 | B0P7 | B1P5 | B2P2 | B4P0 | - | - | - | - |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Three-phase: VZ- $\square$ |  | 20P1 | 20P2 | 20P4 | 20P7 | 21P5 | 22P2 | 24P0 | 25P5 | 27P5 | 2011 | 2015 |
| Motor kW ${ }^{1}$ | For HD setting | 0.12 | 0.25 | 0.4 | 0.75 | 1.5 | 2.2 | 4.0 | 5.5 | 7.5 | 11 | 15 |
|  | For ND setting | 0.18 | 0.37 | 0.75 | 1.1 | 2.2 | 3.0 | 5.5 | 7.5 | 11 | 15 | 18.5 |
|  | Inverter capacity kVA | 0.3 | 0.6 | 1.1 | 1.9 | 3.0 | 4.2 | 6.7 | 9.5 | 13 | 18 | 23 |
|  | Rated output current (A) at HD | 0.8 | 1.6 | 3.0 | 5.0 | 8.0 | 11.0 | 17.5 | 25.0 | 33.0 | 47.0 | 60.0 |
|  | Rated output current (A) at ND | 1.2 | 1.9 | 3.5 | 6.0 | 9.6 | 12.0 | 21.0 | 30.0 | 40.0 | 56.0 | 69.0 |
|  | Max. output voltage | Proportional to input voltage: $0 . .240 \mathrm{~V}$ |  |  |  |  |  |  |  |  |  |  |
|  | Max. output frequency | 400 Hz |  |  |  |  |  |  |  |  |  |  |
|  | Rated input voltage and frequency | Single-phase 200.. $240 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ 3 -phase 200 .. $240 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |
|  | Allowable voltage fluctuation | -15\%..+10\% |  |  |  |  |  |  |  |  |  |  |
|  | Allowable frequency fluctuation | +5\% |  |  |  |  |  |  |  |  |  |  |

1. Based on a standard 4-pole motor for maximum applicable motor output: Heavy Duty (HD) mode with a $150 \%$ overload capacity Normal Duty (ND) mode with a $120 \%$ overlaod capacity

400 V class

| Three-phase: VZ- $\square$ |  | 40P2 | 40P4 | 40P7 | 41P5 | 42P2 | 43P0 | 44P0 | 45P5 | 47P5 | 4011 | 4015 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Motor kW ${ }^{1}$ | For HD setting | 0.2 | 0.4 | 0.75 | 1.5 | 2.2 | 3.0 | 4.0 | 5.5 | 7.5 | 11 | 15 |
|  | For ND setting | 0.37 | 0.75 | 1.5 | 2.2 | 3.0 | 3.7 | 5.5 | 7.5 | 11 | 15 | 18.5 |
|  | Inverter capacity kVA | 0.9 | 1.4 | 2.6 | 3.7 | 4.2 | 5.5 | 7.2 | 9.2 | 14.8 | 18 | 24 |
|  | Rated output current (A) at HD | 1.2 | 1.8 | 3.4 | 4.8 | 5.5 | 7.2 | 9.2 | 14.8 | 18.0 | 24 | 31 |
|  | Rated output current (A) at ND | 1.2 | 2.1 | 4.1 | 5.4 | 6.9 | 8.8 | 11.1 | 17.5 | 23 | 31 | 38 |
|  | Max. output voltage | $0 . .480 \mathrm{~V}$ (proportional to input voltage) |  |  |  |  |  |  |  |  |  |  |
|  | Max. output frequency | 400 Hz |  |  |  |  |  |  |  |  |  |  |
|  | Rated input voltage and frequency | 3-phase 380 .. 480 VAC, $50 / 60 \mathrm{~Hz}$ |  |  |  |  |  |  |  |  |  |  |
|  | Allowable voltage fluctuation | -15\%..+10\% |  |  |  |  |  |  |  |  |  |  |
|  | Allowable frequency fluctuation | +5\% |  |  |  |  |  |  |  |  |  |  |

1. Based on a standard 4-pole motor for maximum applicable motor output: Heavy Duty (HD) mode with a $150 \%$ overload capacity Normal Duty (ND) mode with a $120 \%$ overlaod capacity

## Specifications

Commom specifications

|  | Model number vz- | Specifications |
| :---: | :---: | :---: |
|  | Control methods | Sine wave PWM (V/f control, sensorless current vector control) |
|  | Output frequency range | 0.1.. 400 Hz |
|  | Frequency tolerance | Digital set value: $\pm 0.01 \%\left(-10 . .+50^{\circ} \mathrm{C}\right)$ |
|  |  | Analogue set value: $\pm 0.1 \%\left(25 \pm 10^{\circ} \mathrm{C}\right)$ |
|  | Resolution of frequency set value | Digital set value: $0.01 \mathrm{~Hz}(<100 \mathrm{~Hz}), 0.1 \mathrm{~Hz}(>100 \mathrm{~Hz})$ |
|  |  | Analogue set value: $1 / 1000$ of maximum frequency |
|  | Resolution of output frequency | 0.01 Hz |
|  | Overload capability | Heavy duty use: $150 \%$ rated output current for one minute Normal duty use: $120 \%$ rated output current for one minute |
|  | Frequency set value | $0 . .10 \mathrm{~V}(20 \mathrm{k} \Omega), 4 . .20 \mathrm{~mA}(250 \Omega), 0 . .20 \mathrm{~mA}(250 \Omega)$ Pulse train input, frequency setting value (selectable) |
|  | Braking torque <br> (short term peak torque) | Short-term average deceleration torque: $150 \%$ (up 1.5 kW ), 100\% (for 1.5 kW ), $50 \%$ (for 2.2 kW ), $20 \%$ (fof bigger size) Continous regenerative torque: Aprox $20 \%$ ( $125 \%$ with optional braking resistor, $10 \% \mathrm{ED}, 10 \mathrm{~s}$, braking transistor built itn) |
|  | V/f Characteristics | Possible to program any V/f pattern |
|  | Inputs signals | Seven of the following input signals are selectable: Forward/reverse run (3-wire sequence), fault reset, external fault (NO/NC contact input), multi-step speed operation, Jog command, accel/decel time select, external baseblock, speed search command, UP/DOWN command, accel/decel hold command, LOCAL/REMOTE selection, communication/control circuit terminal selection, mergency stop fault, emergency stop alarm, self test |
|  | Output signals | Following output signals are selectable (NO/NC contact output, 2 photo-coupler outputs): Fault, running, zero speed, speed agree, frequency detection (output frequency <= or => set value), during overtorque detection, minor error, during baseblock, operation mode, inverter run ready, during fault retry, during undervoltage detection, reverse running, during speed search, data output through communication. |
|  | Standard functions | Open-loop vector control, full-range automatic torque boost, slip compensation, 17-step speed operation (max.), restart after momentary power loss, DC injection braking current at stop/start ( $50 \%$ of inverter rated current, 0.5 sec , or less), frequency reference bias/gain, MEMOBUS communications (RS-485/422, max. 115K bps), fault retry, speed search, frequency upper/ lower limit setting, overtorque detection, frequency jump, accel/decel time switch, accel/decel prohibited, S-curve accel/decel, PID control, energy-saving control, constant copy. |
|  | Analogue inputs | 2 analogue inputs, $0 . .10 \mathrm{~V}, 4 . .20 \mathrm{~mA}, 0 . .20 \mathrm{~mA}$ |
|  | Braking/acceleration times | $0.01 . .6000 \mathrm{~s}$ |
|  | Display | Optionally frequency, current or set value |
|  |  | Error and status LED |
|  | Motor overload protection | Electronic thermal overload relay |
|  | Instantaneous overcurrent | Motor coasts to a stop at approx. 250\% of inverter rated current |
|  | Overload | Heavy Duty: Motor coasts to a stop after 1 minute at $150 \%$ of inverter rated output current Normal Duty: Motor coasts to a stop after 1 minute at $120 \%$ of inverter rated output current |
|  | Overvoltage | Motor coasts to a stop if DC bus voltage exceed 410 V (double for 400 V class) |
|  | Undervoltage | Stops when DC bus voltage is approx. 190 V or less (double for 400 V class) (approx. 150 V or less for single-phase series) |
|  | Momentary power loss | Following items are selectable: not provided (stop if power loss is 15 ms or longer), continuous operation if power loss is approx. 0.5 s or shorter, continuous operation |
|  | Cooling fin overheat | Protected by thermister |
|  | Stall prevention level | Stall prevention during acceleration/deceleration and constant speed operation |
|  | Ground fault | Protected by electronic circuit (operation level is approx. $250 \%$ of rated output current) |
|  | Power charge indication | Indicates until the main circuit voltage reaches 50 V . |
|  | Degree of protection | IP20, NEMA1 |
|  | Cooling | Cooling fan is provided for $200 \mathrm{~V}, 0.75 \mathrm{~kW}$ (1HP) (3/single-phase) $400 \mathrm{~V}, 1.5 \mathrm{~kW}(2 \mathrm{HP})$ (3-phase), others are self-cooling |
|  | Ambient humidity | $95 \% \mathrm{RH}$ or less (without condensation) |
|  | Storage temperature | $-20^{\circ} \mathrm{C} . .+60^{\circ} \mathrm{C}$ (short-term temperature during transportation) |
|  | Installation | Indoor (no corrosive gas, dust, etc.) |
|  | Installation height | Max. 1000 m |
|  | Vibration | Up to 1 G at 10 to less than 20 Hz , Up to 0.65 G at 20 to 50 Hz |

Dimensions

## IP 20 type 0.1 to 4 kW

Figure 1
Figure 2


\begin{tabular}{|c|c|c|c|c|c|c|c|c|c|c|c|}
\hline \multirow[b]{2}{*}{Voltage class} \& \multirow[t]{2}{*}{Max. applicable motor output kW} \& \multirow[b]{2}{*}{Inverter model VZA} \& \multirow[b]{2}{*}{Figure} \& \multicolumn{8}{|c|}{Dimensions in mm} <br>
\hline \& \& \& \& W1 \& H1 \& W \& H \& D \& t1 \& H2 \& D1 <br>
\hline \multirow{7}{*}{Single-phase 200 V} \& 0.12 \& B0P1 \& \multirow{3}{*}{1} \& \multirow{3}{*}{56} \& \multirow{6}{*}{118} \& \multirow{3}{*}{68} \& \multirow{6}{*}{128} \& \multirow[b]{2}{*}{76} \& \multirow[b]{2}{*}{3} \& \multirow{6}{*}{5} \& \multirow[b]{2}{*}{6.5} <br>
\hline \& 0.25 \& B0P2 \& \& \& \& \& \& \& \& \& <br>
\hline \& 0.55 \& B0P4 \& \& \& \& \& \& 108 \& \multirow{4}{*}{5} \& \& 38.5 <br>
\hline \& 1.1 \& B0P7 \& \multirow{3}{*}{2} \& \multirow[t]{2}{*}{96} \& \& \multirow[t]{2}{*}{108} \& \& 137.5 \& \& \& \multirow[t]{2}{*}{58} <br>
\hline \& 1.5 \& B1P5 \& \& \& \& \& \& 154 \& \& \& <br>
\hline \& 2.2 \& B2P2 \& \& 128 \& \& 140 \& \& 163 \& \& \& 65 <br>
\hline \& 4.0 \& B4P0 \& \multicolumn{9}{|c|}{Under development} <br>
\hline \multirow{11}{*}{Three-phase 200 V} \& 0.12 \& 20P1 \& \multirow{4}{*}{1} \& \multirow{4}{*}{56} \& \multirow{7}{*}{118} \& \multirow{4}{*}{68} \& \multirow{7}{*}{128} \& 76 \& \multirow{7}{*}{3

5} \& \multirow{7}{*}{5} \& \multirow[t]{2}{*}{6.5} <br>
\hline \& 0.25 \& 20P2 \& \& \& \& \& \& \& \& \& <br>
\hline \& 0.55 \& 20P4 \& \& \& \& \& \& 108 \& \& \& <br>
\hline \& 1.1 \& 20P7 \& \& \& \& \& \& 128 \& \& \& 38.5 <br>
\hline \& 1.5 \& 21P5 \& \multirow{3}{*}{2} \& \multirow[b]{2}{*}{96} \& \& \multirow[b]{2}{*}{108} \& \& 129 \& \& \& \multirow[b]{2}{*}{58} <br>
\hline \& 2.2 \& 22P2 \& \& \& \& \& \& 137.5 \& \& \& <br>
\hline \& 4.0 \& 24P0 \& \& 128 \& \& 140 \& \& 143 \& \& \& 65 <br>
\hline \& 5.5 \& 25P5 \& \multicolumn{9}{|c|}{\multirow{4}{*}{Under development}} <br>
\hline \& 7.5 \& 27P5 \& \& \& \& \& \& \& \& \& <br>
\hline \& 11 \& 2011 \& \& \& \& \& \& \& \& \& <br>
\hline \& 15 \& 2015 \& \& \& \& \& \& \& \& \& <br>
\hline \multirow{11}{*}{Three-phase 400 V} \& 0.37 \& 40P2 \& \multirow{7}{*}{2} \& \multirow{6}{*}{96} \& \multirow{7}{*}{118} \& \multirow{6}{*}{108} \& \multirow{7}{*}{128} \& 81 \& \multirow{7}{*}{5} \& \multirow{7}{*}{5} \& 10 <br>
\hline \& 0.55 \& 40P4 \& \& \& \& \& \& 99 \& \& \& 28 <br>
\hline \& 1.1 \& 40P7 \& \& \& \& \& \& 137.5 \& \& \& \multirow{4}{*}{58} <br>
\hline \& 1.5 \& 41P5 \& \& \& \& \& \& \multirow{3}{*}{154} \& \& \& <br>
\hline \& 2.2 \& 42P2 \& \& \& \& \& \& \& \& \& <br>
\hline \& 3.0 \& 43P0 \& \& \& \& \& \& \& \& \& <br>
\hline \& 4.0 \& 44P0 \& \& 128 \& \& 140 \& \& 143 \& \& \& 65 <br>
\hline \& 5.5 \& 45P5 \& \multicolumn{9}{|c|}{\multirow{4}{*}{Under development}} <br>
\hline \& 7.5 \& 47P5 \& \& \& \& \& \& \& \& \& <br>
\hline \& 11 \& 4011 \& \& \& \& \& \& \& \& \& <br>
\hline \& 15 \& 4015 \& \& \& \& \& \& \& \& \& <br>
\hline
\end{tabular}

## Footprint Filters



| Schaffner model |  | Dimensions |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A | B | C | D | E | F | G | H | I | J | K | L |
| $3 \times 200 \mathrm{~V}$ | A1000-FIV2010-SE | 194 | 82 | 50 | 160 | 181 | 62 | 5.3 | M5 | 25 | 56 | 118 | M4 |
|  | A1000-FIV2020-SE | 169 | 111 | 50 | 135 | 156 | 91 | 5.5 | M5 | 25 | 96 | 118 | M4 |
|  | A1000-FIV2030-SE | 174 | 144 | 50 | 135 | 161 | 120 | 5.3 | M5 | 25 | 128 | 118 | M4 |
| 1x200 V | A1000-FIV1010-SE | 169 | 71 | 45 | 135 | 156 | 51 | 5.3 | M5 | 22 | 56 | 118 | M4 |
|  | A1000-FIV1020-SE | 169 | 111 | 50 | 135 | 156 | 91 | 5.3 | M5 | 25 | 96 | 118 | M4 |
|  | A1000-FIV1030-SE | 174 | 144 | 50 | 135 | 161 | 120 | 5.3 | M5 | 25 | 128 | 118 | M4 |
|  | A1000-FIV1040-SE | 174 | 144 | 50 | 135 | 161 | 150 | 5 | M5 | 25 | 158 | 118 | M4 |
| $3 \times 400 \mathrm{~V}$ | A1000-FIV3005-SE | 169 | 111 | 45 | 135 | 156 | 91 | 5.3 | M5 | 22 | 96 | 118 | M4 |
|  | A1000-FIV3010-SE | 169 | 111 | 45 | 135 | 156 | 91 | 5.3 | M5 | 22 | 96 | 118 | M4 |
|  | A1000-FIV3020-SE | 174 | 144 | 50 | 135 | 161 | 120 | 5 | M5 | 25 | 128 | 118 | M4 |
|  | A1000-FIV3030-SE | 304 | 184 | 56 | 264 | 288 | 150 | 6 | M5 | 28 | 164 | 244 | M5 |

## DIN rail mounting bracket



EZZ08122B


EZZ08122D


| Inverter |  | DIN rail mounting bracket |
| :---: | :---: | :---: |
| 3-phase 200 VAC | VZ - 20P1/ 20P2 / 20P4/ 20P7 | EZZ08122A |
|  | VZ-21P5/ 22P2 | EZZ08122B |
|  | VZ - 24P0 | EZZ08122C |
| Single-phase 200 VAC | VZ - B0P1/ B0P2/ B0P4 | EZZ08122A |
|  | VZ - B0P7/ B1P5 | EZZ08122B |
|  | VZ - B2P2 | EZZ08122C |
|  | VZ - B4P0 | EZZ08122D |
| 3-phase 400 VAC | VZ - 40P2/ 40P4/ 40P7/ 41P5/ 42P2 | EZZ08122B |
|  | VZ-44P0 | EZZ08122C |

## Installation

## Standard connections

V1000 Connection Diagram

| European Standard Spec. | DC Reactor <br> (Option) | Braking Resistor <br> (Option) |
| :--- | :--- | :--- |



## Main circuit

| Terminal | Name | Function (signal level) |
| :---: | :--- | :--- |
| R/L1, S/L2, T/L3 | Main circuit power supply input | Used to connect line power to the drive. <br> Drives with single-phase 200 V input power use only terminals R/L1 and S/L2 <br> (T/L3 is not connected to anything) |
| U/T1, V/T2, W/T3 | Inverter output | Used to connect the motor |
| $\mathbf{B 1 , ~ B 2 ~}$ | Braking resistor connection | Available for connecting a braking resistor or the braking resistor unit option. |
| $\mathbf{+ 2 , + 1}$ | DC reactor connection | Remove the short bar between +2 and +1 when connecting DC reactor (option) |
| $\mathbf{+ 1 , ~}$ | DC power supply input | For power supply input (+1: positive electrode; - : negative electrode)* |
| $\Theta$ | Grounding | For grounding (grounding should conform to the local grounding code.) |
| $\boldsymbol{m}$ |  |  |

## Control Circuit

| Type | No. | Signal name | Function | Signal level |
| :---: | :---: | :---: | :---: | :---: |
|  | S1 | Multi-function input selection 1 | Factory setting: runs when CLOSED, stops when OPEN. | 24 VDC, 8 mA photocoupler insulation |
|  | S2 | Multi-function input selection 2 | Factory setting: runs when CLOSED, stops when OPEN. |  |
|  | S3 | Multi-function input selection 3 | Factory setting: External Fault (N.O.) |  |
|  | S4 | Multi-function input selection 4 | Factory setting: Fault reset |  |
|  | S5 | Multi-function input selection 5 | Factory setting: Multi-step speed cmd 1 |  |
|  | S6 | Multi-function input selection 6 | Factory setting: Multi-step speed cmd 2 |  |
|  | SC | Multi-function input selection Common | Common for control signal |  |
|  | RP | Main Speed Cmd Pulse Train Input | 32 kHz max. |  |
|  | FS | Power Supply for Frequency Setting | +10 V (allowable max current 20 mA ) |  |
|  | FR1 | Main Speed Freq Ref | Voltage input or current input <br> 0 to $+10 \mathrm{VDC}(20 \mathrm{k} \Omega)$ (resolution 1/1000) <br> 4 to $20 \mathrm{~mA}(250 \Omega)$ or 0 to $20 \mathrm{~mA}(250 \Omega)$ Resolution: $1 / 500$ |  |
|  | FR2 |  |  |  |  |
|  | FC | Frequency reference common | 0 V |  |
| Fast <br> Stop <br> Cmd | HC | Power Supply Fast Stop Cmd | +24 V (max allowable current 10 mA ) |  |
|  | H1 | Special Digital input | Open: Fast Stop Closed: Normal Operation |  |
|  | H2 | Special Digital input |  |  |  |
|  | MA | NO contact output | Factory setting: "fault" | Contact capacity 250 VAC, <br> 1 A or less 30 VDC, 1 A or less |
|  | MB | NC Output |  |  |
|  | MC | Relay Output common |  |  |
|  | P1 | Photocoupler output 1 | Factory setting: During run | Photocoupler output: +48 VDC, 50 mA or less |
|  | P2 | Photocoupler output 2 | Factory setting: Frequency Agree |  |
|  | PC | Photocoupler output common | 0 V |  |
| Analog output signals | PM | Pulse train Output | max 33 kHz |  |
|  | AM | Analog monitor output | Factory setting: "output frequency" 0 to +10 V output Resolution: 1/1000 | 0 to 10 V 2 mA or less <br> Resolution: 8 bits |
|  | AC | Analog monitor common | 0 V |  |
|  | R+ | Communication input (+) | For MEMOBUS communication operation by RS-485 or RS-422 communication is available. | RS-485/422 MEMOBUS protocol |
|  | R- | Communication input (-) |  |  |
|  | S+ | Communication output (+) |  |  |
|  | S- | Communication output (-) |  |  |



## Inverter heat loss

Three-phase 200 V class

| Model VZ |  | 20P1 | 20P2 | 20P4 | 20P7 | 21P5 | 22P2 | 24P0 | 25P5 | 27P5 | 2011 | 2015 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter capacity kVA |  | 0.3 | 0.6 | 1.1 | 1.9 | 3.0 | 4.2 | 6.7 | 9.5 | 13 | 18 | 23 |
| Rated current (A) at HD |  | 0.8 | 1.6 | 3 | 5 | 8 | 11 | 17.5 | 25 | 33 | 47.0 | 60.0 |
| Rated current (A) at ND |  | 1.2 | 1.9 | 3.5 | 6.0 | 9.6 | 12.0 | 21.0 | 30.0 | 40.0 | 56.0 | 69.0 |
|  | Fin | 4.3 | 7.9 | 16.1 | 27.4 | 54.8 | 70.7 | 110.5 | 231.5 | 239.5 | 347.6 | 437.7 |
|  | Inside unit | 7.3 | 8.8 | 11.5 | 15.9 | 23.8 | 30.0 | 43.3 | 72.2 | 81.8 | 117.6 | 151.4 |
|  | Total heat loss | 11.6 | 16.7 | 27.7 | 43.3 | 78.6 | 100.6 | 153.8 | 303.7 | 321.3 | 465.2 | 5891. |
|  | Fin | 4.7 | 7.2 | 14.0 | 35.6 | 48.6 | 57.9 | 93.3 | 236.8 | 258.8 | 342.8 | 448.5 |
|  | Inside unit | 7.9 | 9.4 | 13.4 | 16.9 | 25.0 | 29.6 | 45.0 | 87.2 | 11.4 | 149.1 | 182.2 |
|  | Total heat loss | 12.6 | 16.6 | 28.5 | 43.1 | 73.6 | 87.5 | 138.2 | 324.0 | 370.3 | 491.9 | 630.7 |

Single-phase $\mathbf{2 0 0}$ V class

| Model VZ |  | B0P1 | B0P2 | B0P4 | B0P7 | B1P5 | B2P2 | B4P0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter capacity kVA |  | 0.3 | 0.6 | 1.1 | 1.9 | 3.0 | 4.2 | 6.7 |
| Rated current (A) at HD |  | 0.8 | 1.6 | 3 | 5 | 8 | 11 | 17.5 |
| Rated current (A) at ND |  | 1.2 | 1.9 | 3.5 | 6.0 | 9.6 | 12.0 | 21.0 |
|  | Fin | 4.3 | 7.9 | 16.1 | 42.5 | 54.8 | 70.7 | 110.5 |
|  | Inside unit | 7.4 | 8.9 | 11.5 | 19.0 | 25.9 | 34.1 | 51.4 |
|  | Total heat loss | 11.7 | 16.7 | 27.7 | 61.5 | 80.7 | 104.8 | 161.9 |
|  | Fin | 4.7 | 7.2 | 15.1 | 26.2 | 48.6 | 57.9 | 93.3 |
|  | Inside unit | 8.4 | 9.6 | 14.3 | 20.8 | 29.0 | 36.3 | 58.5 |
|  | Total heat loss | 13.1 | 16.8 | 28.3 | 56.5 | 77.6 | 94.2 | 151.8 |

Three-phase 400 V class

| Model VZ |  | 40P2 | 40P4 | 40P7 | 41P5 | 42P2 | 43P0 | 44P0 | 45P5 | 47P5 | 4011 | 4015 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverter capacity kVA |  | 0.9 | 1.4 | 2.6 | 3.7 | 4.2 | 5.5 | 7.2 | 9.2 | 14.8 | 18 | 24 |
| Rated current (A) at HD |  | 1.2 | 1.8 | 3.4 | 4.8 | 5.5 | 7.2 | 9.2 | 14.8 | 18.0 | 24 | 31 |
| Rated current (A) at ND |  | 1.2 | 2.1 | 4.1 | 5.4 | 6.9 | 8.8 | 11.1 | 17.5 | 23 | 31 | 38 |
|  | Fin | 19.2 | 28.9 | 42.3 | 70.7 | 81.0 | 84.6 | 107.2 | 166.0 | 207.1 | 266.9 | 319.1 |
|  | Inside unit | 11.4 | 14.9 | 17.9 | 26.2 | 30.7 | 32.9 | 41.5 | 62.7 | 78.1 | 105.9 | 126.6 |
|  | Total heat loss | 30.6 | 43.7 | 60.2 | 96.9 | 111.7 | 117.5 | 148.7 | 228.7 | 285.2 | 372.7 | 445.8 |
|  | Fin | 8.2 | 15.5 | 26.4 | 37.5 | 49.7 | 55.7 | 71.9 | 170.3 | 199.5 | 268.6 | 298.7 |
|  | Inside unit | 9.2 | 13.1 | 15.8 | 20.0 | 26.3 | 29.4 | 43.6 | 78.1 | 105.3 | 142.8 | 152.2 |
|  | Total heat loss | 17.4 | 28.6 | 42.2 | 57.5 | 76.0 | 85.1 | 115.5 | 248.4 | 304.8 | 411.4 | 450.9 |

## y omron

## Connections for braking resistor



## AC reactor



| 200 V class |  |  | 400 V class |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Max. applicable motor output kW | $\underset{A}{\text { Current value }}$ | $\begin{gathered} \text { Inductance } \\ \mathrm{mH} \end{gathered}$ | Max. applicable motor output kW | Current value A | Inductance mH |
| 0.12 | 2.0 | 2.0 | ---- |  |  |
| 0.25 | 2.0 | 2.0 | 0.2 | 1.3 | 18.0 |
| 0.55 | 2.5 | 4.2 | 0.4 |  |  |
| 1.1 | 5 | 2.1 | 0.75 | 2.5 | 8.4 |
| 1.5 | 10 | 1.1 | 1.5 | 5 | 4.2 |
| 2.2 | 15 | 0.71 | 2.2 | 7.5 | 3.6 |
| 4.0 | 20 | 0.53 | 4.0 | 10 | 2.2 |
| 5.5 | 30 | 0.35 | 5.5 | 15 | 1.42 |
| 7.5 | 40 | 0.265 | 7.5 | 20 | 1.06 |
| 11 | 60 | 0.18 | 11 | 30 | 0.7 |
| 15 | 80 | 0.13 | 15 | 40 | 0.53 |

## DC reactor



DC reactor

| 200 V class |  |  | 400 V class |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Max. applicable motor output kW | Current value A | Inductance mH | Max. applicable motor output kW | Current value A | Inductance mH |
| 0.12 | 5.4 | 8 | -------- |  |  |
| 0.25 |  |  | 0.2 |  |  |
| 0.55 |  |  | 0.4 | 3.2 | 28 |
| 1.1 |  |  | 0.75 |  |  |
| 1.5 | 18 | 3 | 1.5 | 5.7 | 11 |
| 2.2 |  |  | 2.2 |  |  |
| 4.0 |  |  | 4.0 | 12 | 6.3 |
| 5.5 | 36 | 1 | 5.5 | 23 | 3.6 |
| 7.5 |  |  | 7.5 |  |  |
| 11 | 72 | 0.5 | 11 | 33 | 1.9 |
| 15 |  |  | 15 |  |  |

## Ordering information



V1000

| Specifications |  |  |  |  | Model |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Heavy Duty |  | Normal Duty |  | Standard | Built-in filter |
| $1 \times 200 \mathrm{~V}$ | 0.12 kW | 0.8 A | 0.18 kW | 0.8 A | VZAB0P1BAA | VZAB0P1HAA |
|  | 0.25 kW | 1.6 A | 0.37 kW | 1.6 A | VZAB0P2BAA | VZAB0P2HAA |
|  | 0.55 kW | 3.0 A | 0.75 kW | 3.5 A | VZAB0P4BAA | VZAB0P4HAA |
|  | 1.1 kW | 5.0 A | 1.1 kW | 6.0 A | VZAB0P7BAA | VZAB0P7HAA |
|  | 1.5 kW | 8.0 A | 2.2 kW | 9.6 A | VZAB1P5BAA | VZAB1P5HAA |
|  | 2.2 kW | 11.0 A | 3.0 kW | 12.0 A | VZAB2P2BAA | VZAB2P2HAA |
|  | 4.0 kW | 17.5 A | 5.5 kW | 21.0 A | VZAB4P0BAA | VZAB4P0HAA |
| $3 \times 200 \mathrm{~V}$ | 0.12 kW | 0.8 A | 0.18 kW | 0.8 A | VZA20P1BAA | VZA20P1HAA |
|  | 0.25 kW | 1.6 A | 0.37 kW | 1.6 A | VZA20P2BAA | VZA20P2HAA |
|  | 0.55 kW | 3.0 A | 0.75 kW | 3.5 A | VZA20P4BAA | VZA20P4HAA |
|  | 1.1 kW | 5.0 A | 1.1 kW | 6.0 A | VZA20P7BAA | VZA20P7HAA |
|  | 1.5 kW | 8.0 A | 2.2 kW | 9.6 A | VZA21P5BAA | VZA21P5HAA |
|  | 2.2 kW | 11.0 A | 3.0 kW | 12.0 A | VZA22P2BAA | VZA22P2HAA |
|  | 4.0 kW | 17.5 A | 5.5 kW | 21.0 A | VZA24P0BAA | VZA24P0HAA |
|  | 5.5 kW | 25.0 A | 7.5 kW | 30.0 A | VZA25P5FAA | VZA25P5HAA |
|  | 7.5 kW | 33.0 A | 11.0 kW | 40.0 A | VZA27P5FAA | VZA27P5HAA |
|  | 11 kW | 47.0 A | 15.0 kW | 56.0 A | VZA2011FAA | VZA2011HAA |
|  | 15 kW | 60.0 A | 18.5 kW | 69.0 A | VZA2015FAA | VZA2015HAA |
| $3 \times 400 \mathrm{~V}$ | 0.37 kW | 1.2 A | 0.18 kW | 1.2 A | VZA40P2BAA | VZA40P2HAA |
|  | 0.55 kW | 1.8 A | 0.37 kW | 2.1 A | VZA40P4BAA | VZA40P4HAA |
|  | 1.1 kW | 3.4 A | 0.75 kW | 4.1 A | VZA40P7BAA | VZA40P7HAA |
|  | 1.5 kW | 4.8 A | 1.1 kW | 5.4 A | VZA41P5BAA | VZA41P5HAA |
|  | 2.2 kW | 5.5 A | 2.2 kW | 6.9 A | VZA42P2BAA | VZA42P2HAA |
|  | 3.0 kW | 7.2 A | 3.0 kW | 8.8 A | VZA43P0BAA | VZA43P0HAA |
|  | 4.0 kW | 9.2 A | 5.5 kW | 11.1 A | VZA44P0BAA | VZA44P0HAA |
|  | 5.5 kW | 14.8 A | 7.5 kW | 17.5 A | VZA45P5FAA | VZA45P5HAA |
|  | 7.5 kW | 18.0 A | 11.0 kW | 23.0 A | VZA47P5FAA | VZA47P5HAA |
|  | 11 kW | 24.0 A | 15.0 kW | 31.0 A | VZA4011FAA | VZA4011HAA |
|  | 15 kW | 31.0 A | 18.5 kW | 38.0 A | VZA4015FAA | VZA4015HAA |

(1) Line filters

| Inverter |  | Line filter |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Voltage | Model VZ | Schaffner | Rated current (A) | Weight (kg) |
|  | 20P1 / 20P2 / 20P4 / 20P7 | A1000-FIV2010-SE | 10 | 0.8 |
|  | 21P5 / 22P2 | A1000-FIV2020-SE | 20 | 1.0 |
|  | 24P0 | A1000-FIV2030-SE | 30 | 1.1 |
| 3-Phase 200 VAC | 25P5 / 27P5 | Under development |  |  |
|  | 2011 |  |  |  |
|  | 2015 |  |  |  |
| Single-Phase 200 VAC | B0P1 / BOP2 / B0P4 | A1000-FIV1010-SE | 10 | 0.6 |
|  | B0P7 / B1P5 | A1000-FIV1020-SE | 20 | 1.0 |
|  | B2P2 | A1000-FIV1030-SE | 30 | 1.1 |
|  | B4P0 | A1000-FIV1040-SE | 40 | 1.2 |
| 3-Phase 400 VAC | 40P2 / 40P4 | A1000-FIV3005-SE | 5 | 1.0 |
|  | 40P7 / 41P5 / 42P2 | A1000-FIV3010-SE | 10 | 1.0 |
|  | 43P0 / 44P0 | A1000-FIV3020-SE | 15 | 1.1 |
|  | 45P5 / 47P5 | Under development |  |  |
|  | 4011 |  |  |  |
|  | 4015 |  |  |  |

## (2) Communication cards

| Type | Model | Description | Function |
| :---: | :---: | :---: | :---: |
|  | SI-N3 | DeviceNet option card | - Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through DeviceNet communication with the host controller. |
|  | SI-P3 | PROFIBUS-DP option card | - Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through PROFIBUS-DP communication with the host controller. |
|  | SI-S3 | Can open option card | - Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through CANopen communication with the host controller. |
|  | A1000-CRT1 | CompoNet option card | - Used for running or stopping the inverter, setting or referencing parameters, and monitoring output frequency, output current, or similar items through CompoNet communication with the host controller. |

(3) Accessories

| Types | Model | Description | Functions |
| :---: | :---: | :---: | :---: |
|  | JVOP-180 | LCD remote operator | LCD Display operator with language support |
| © <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br> 0 <br>  | JVOP-181 | USB converter | USB converter unit with copy and backup function |
|  | 72606-WV001 | Remote operator cable (1 m) | Cable for connecting remote operator |
|  | 72606-WV003 | Remote operator cable (3 m) |  |
|  | PS-UDC24 | 24 VDC option board | 24V DC control board power supply |

(4) Computer software

| Types | Model | Description | Installation |
| :---: | :---: | :---: | :---: |
|  | CX-drive | Computer software | Configuration and monitoring software tool |
|  | CX-One | Computer software | Configuration and monitoring software tool |
|  |  |  |  |

(5) Braking unit, braking resistor unit

| Inverter |  |  |  |  | Braking resistor unit |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Max. applicable motor output kW | Inverter model VZ |  | Connectable min. resistance $\Omega$ | Inverter-mounted type (3\%ED, 10 sec max) |  |  |  |
| Voltage |  | Three-phase | Single-phase |  | ERF-150WJ_ | Resistance $\Omega$ | No. of used | Braking torque \% |
| $\begin{gathered} 200 \mathrm{~V} \\ \text { (single-/ } \\ \text { three-phase) } \end{gathered}$ | 0.12 | 20P1 | B0P1 | 300 | 401 | 400 | 1 | 220 |
|  | 0.25 | 20P2 | B0P2 | 300 | 401 | 400 | 1 | 220 |
|  | 0.55 | 20P4 | B0P4 | 200 | 201 | 200 | 1 | 220 |
|  | 1.1 | 20P7 | B0P7 | 120 | 201 | 200 | 1 | 125 |
|  | 1.5 | 21P5 | B1P5 | 60 | 101 | 100 | 1 | 125 |
|  | 2.2 | 22P2 | B2P2 | 60 | 700 | 70 | 1 | 120 |
|  | 4.0 | 24P0 | B4P0 | 32 | 620 | 62 | 1 | 100 |
|  | 5.5 | 25P5 | - | 16 | --- | --- |  |  |
|  | 7.5 | 27P5 | - | 9.6 |  |  |  |  |
|  | 11 | 2011 |  | 9.6 |  |  |  |  |
|  | 15 | 2015 |  | 9.6 |  |  |  |  |
| 400 V (threephase) | 0.37 | 40P2 | - | 750 | 751 | 750 | 1 | 230 |
|  | 0.55 | 40P4 | - | 750 | 751 | 750 | 1 | 230 |
|  | 1.1 | 40P7 | - | 510 | 751 | 750 | 1 | 130 |
|  | 1.5 | 41P5 | - | 240 | 401 | 400 | 1 | 125 |
|  | 2.2 | 42P2 | - | 200 | 301 | 300 | 1 | 115 |
|  | 3.0 | 43P0 | - | 100 | 401 | 400 | 2 | 105 |
|  | 4.0 | 44P0 | - |  |  |  |  |  |
|  | 5.5 | 45P5 | - | 32 | --- | --- |  |  |
|  | 7.5 | 47P5 | - | 32 |  |  |  |  |  |  |
|  | 11 | 4011 | - | 20 |  |  |  |  |  |  |
|  | 15 | 4015 | - | 20 |  |  |  |  |  |  |

OMRON EUROPE B.V. Wegalaan 67-69, NL-2132 JD, Hoofddorp, The Netherlands. Tel: +31 (0) 235681300 Fax: +31 (0) 235681388 www.omron-industrial.com

| Austria | France |
| :---: | :---: |
| Tel: +43 (0) 1801900 | Tel: +33 (0) 156637000 |
| www.omron.at | www.omron.fr |
| Belgium | Germany |
| Tel: +32 (0) 24662480 | Tel: +49 (0) 217368000 |
| www.omron.be | www.omron.de |
| Czech Republic | Hungary |
| Tel: +420 234602602 | Tel: +36 (0) 13993050 |
| www.omron-industrial.cz | www.omron.hu |
| Denmark | Italy |
| Tel: +45434400 11 | Tel: +39 0232681 |
| www.omron.dk | www.omron.it |
| Finland | Middle East \& Africa |
| Tel: +358 (0) 207464200 | Tel: +31 (0) 235681100 |
| www.omron.fi | www.omron-industrial.com |

Netherlands
Tel: +31 (0) 235681100
www.omron.nl

## Norway

Tel: +47 (0) 22657500
www.omron.no
Poland
Tel: +48 (0) 226457860
www.omron.pl

Portugal
Tel: +351 219429400
www.omron.pt

## Russia

Tel: +7 4957452664
www.omron-industrial.ru

Spain
Tel: +34 913777900
www.omron.es

## Sweden

Tel: +46 (0) 86323500
www.omron.se
Switzerland
Tel: +41 (0) 417481313
www.omron.ch
Turkey
Tel: +90 (0) 2164740040 www.omron.com.tr

## United Kingdom

Tel: +44 (0) 8707520861
www.omron.co.uk

## More Omron representatives

www.omron-industrial.com

## Control Systems

- Programmable logic controllers • Human-machine interfaces • Remote I/O


## Motion \& Drives

- Motion controllers • Servo systems • Inverters


## Control Components

- Temperature controllers • Power supplies • Timers • Counters • Programmable relays
- Digital panel indicators • Electromechanical relays • Monitoring products • Solid-state relays
- Limit switches • Pushbutton switches • Low voltage switch gear


## Sensing \& Safety

- Photoelectric sensors • Inductive sensors • Capacitive \& pressure sensors • Cable connectors
- Displacement \& width-measuring sensors • Vision systems • Safety networks • Safety sensors
- Safety units/relay units • Safety door/guard lock switches

